

Blurring the boundary between dynamics and physics in weather and climate models

Tim Palmer
University of Oxford



$$\rho \left(\frac{\partial}{\partial t} + \mathbf{u} \cdot \nabla \right) \mathbf{u} = \rho \mathbf{g} - \nabla p + \nu \nabla^2 \mathbf{u}$$

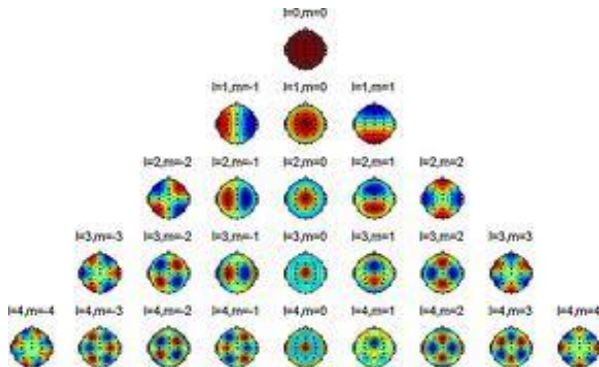
Resolved scales

The Canonical Numerical Ansatz

Unresolved scales

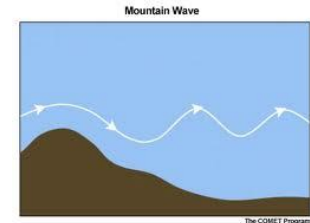
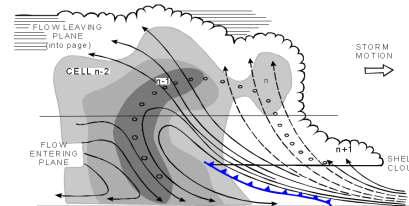
Dynamical Core

$$z = \sum_{m,l} \hat{a}_{ml} z_{ml} e^{iml} P_l^m(f)$$



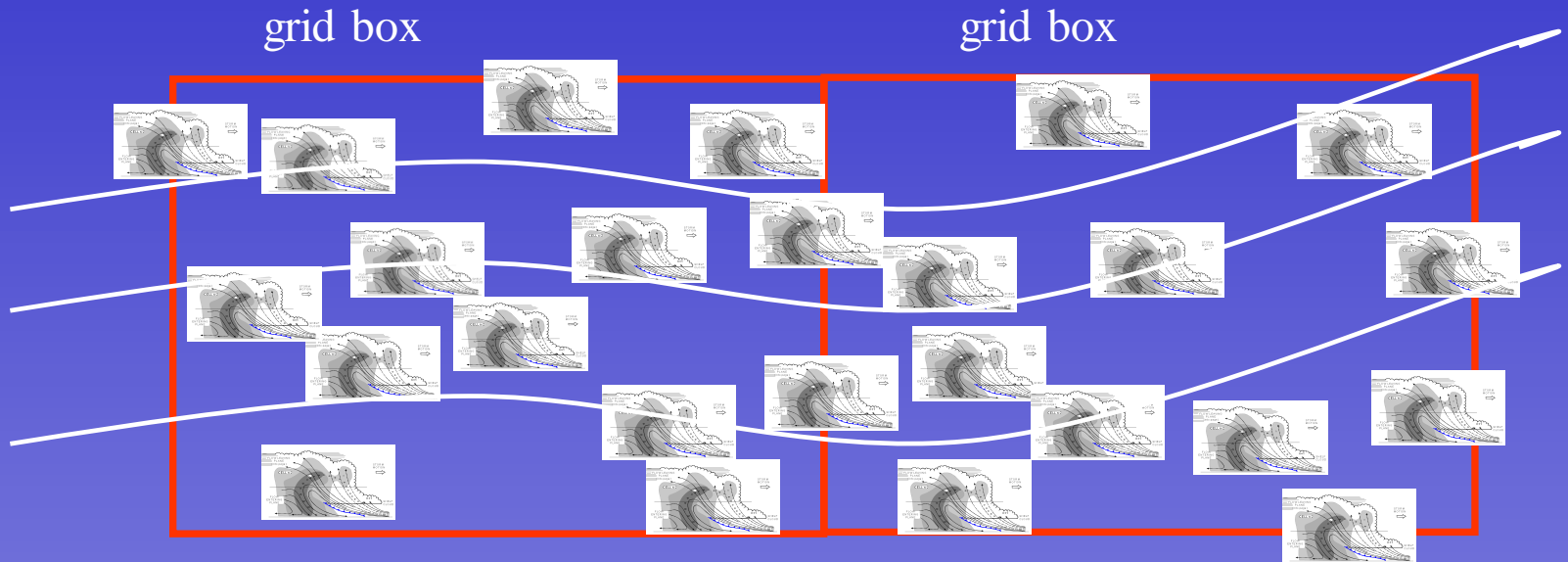
Parametrisations

$$P(X_{\text{Tr}}; a)$$

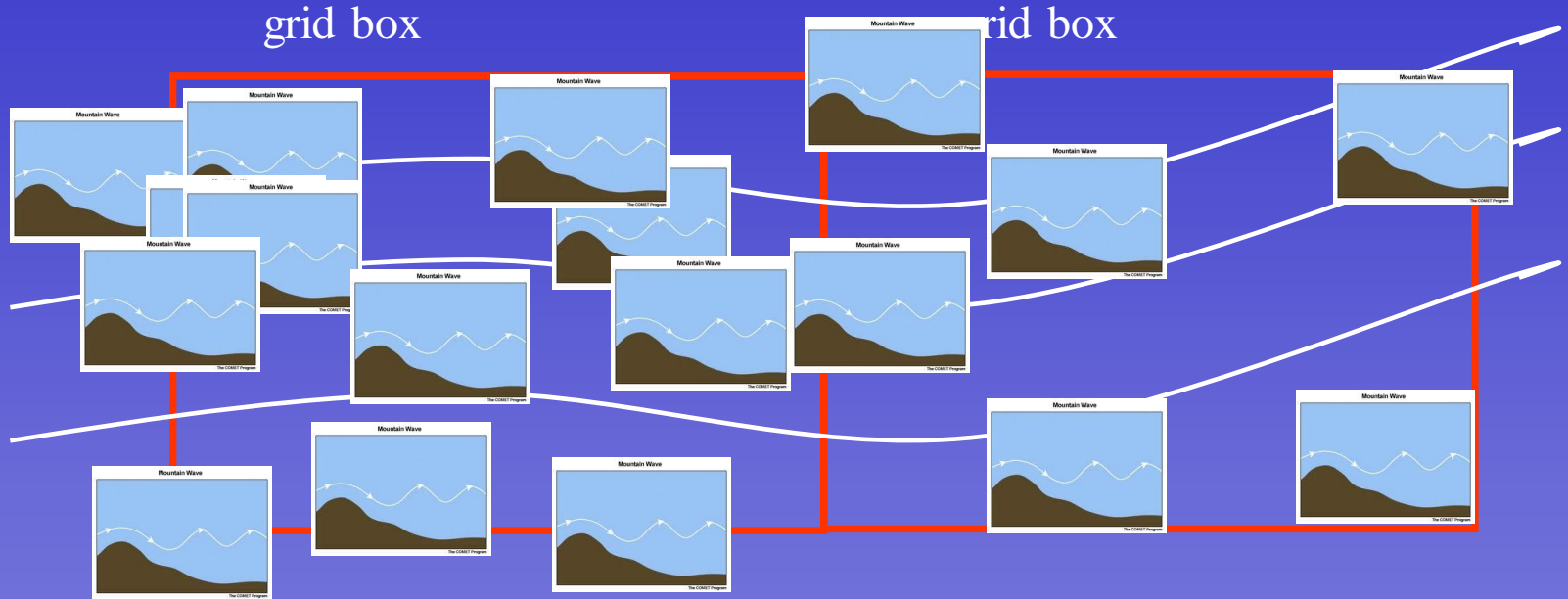


$$D = P$$

... ie the world looks like this

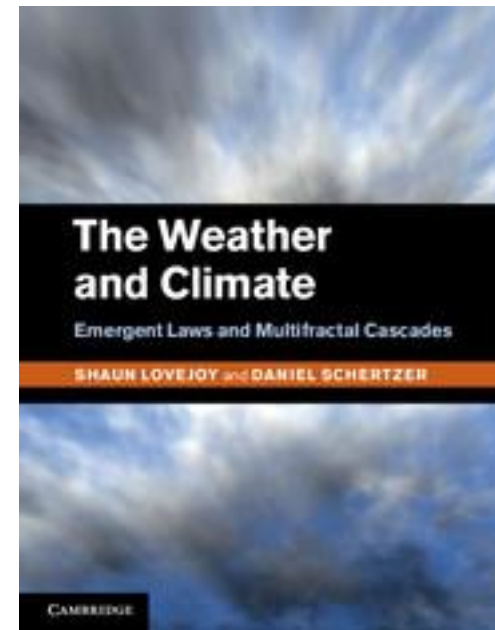
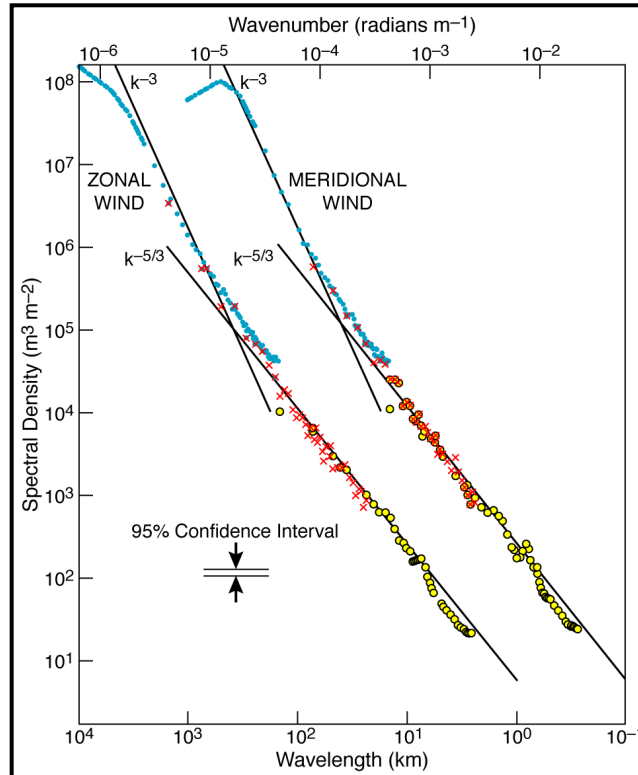


... or this

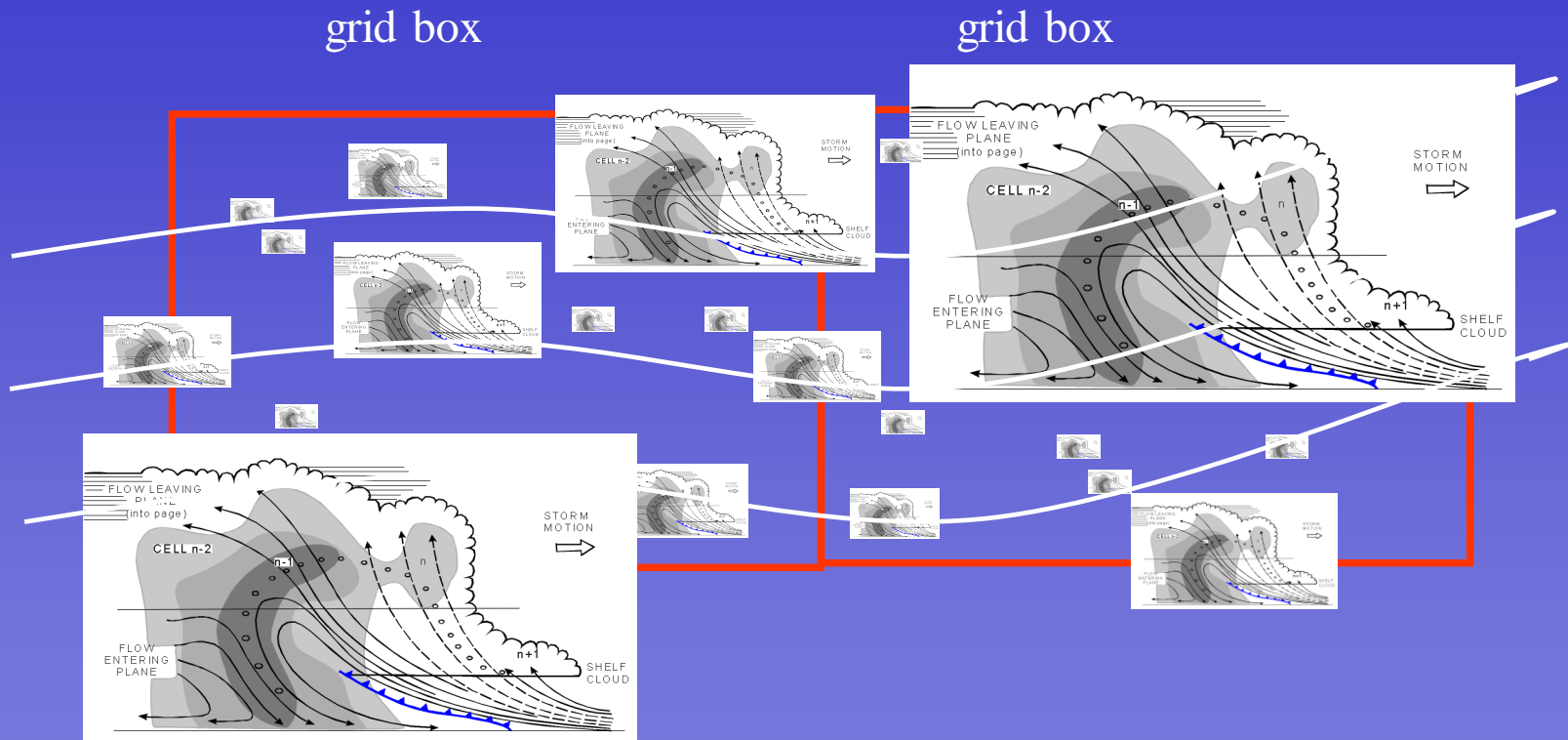


... then the Canonical Numerical Ansatz for
solving the underlying PDEs
would be well posed

But reality is
more like this...
(Nastrom and
Gage, 1985)!

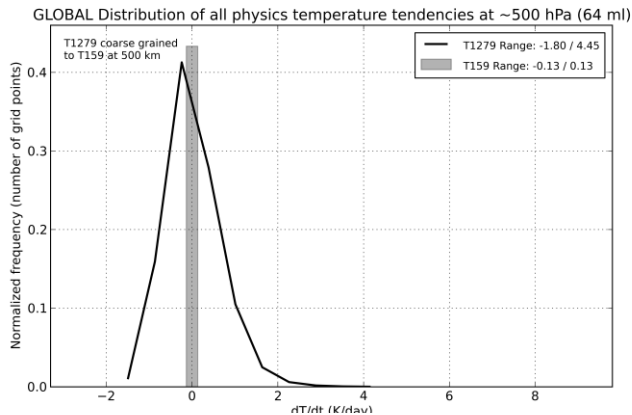


The reality of the situation

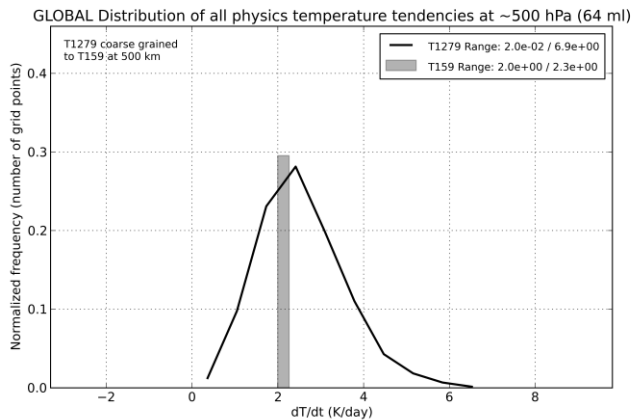


cannot be described by a simple deterministic formula

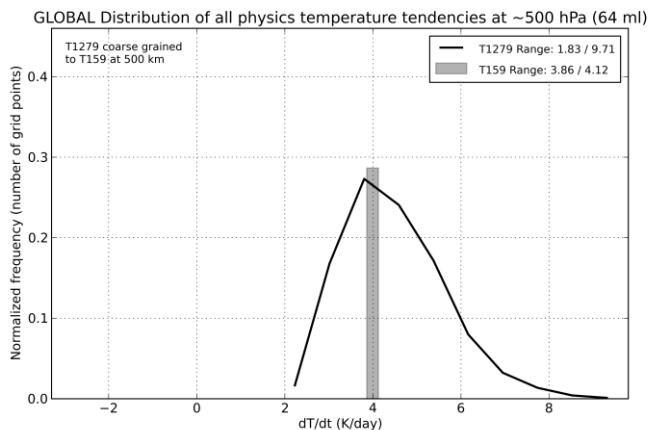
Small
tendency



Medium
tendency



Large
tendency



Callado-Palares and Shutts, 2013.

Coarse-graining (Shutts and Palmer, 2007)

Assume T1279 (16km) model = “truth”.

Assume T159 coarse-grain “model” grid.

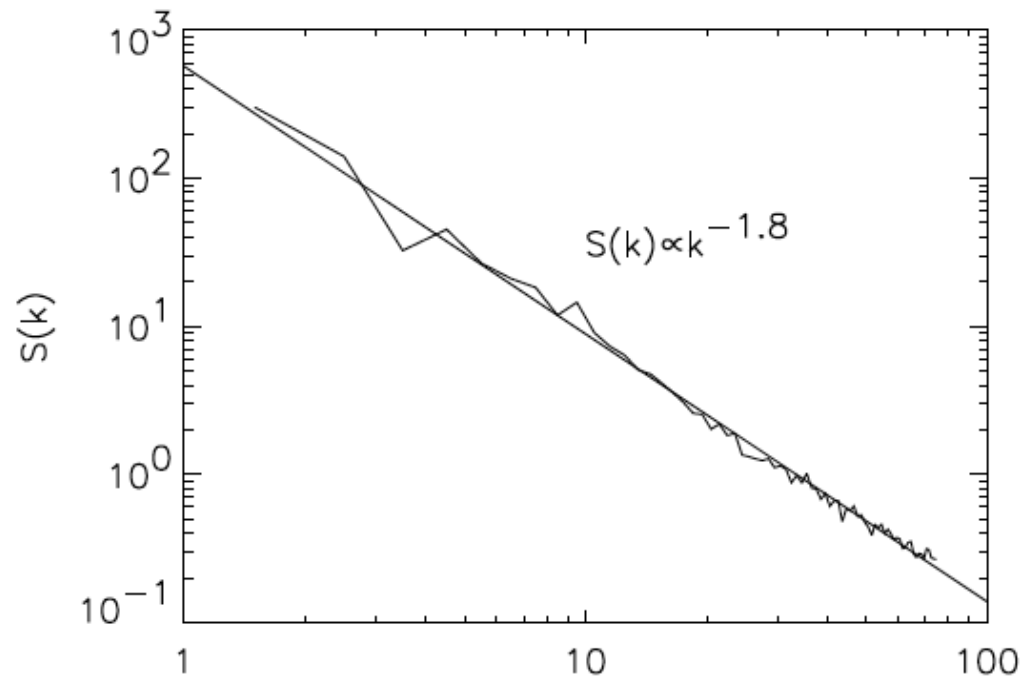
Bar= Subset of T159 total temperature parametrisation tendencies driven by T1279 coarse-grain fields.

Curve= Corresponding “true” sub-T159-scale tendency conditioned on T1279 coarse-grain averaged fields.

le when the parametrisations think the sub-grid pdf is a thin hat function, the reality is a much broader pdf.

The standard deviation increases with parametrised tendency – consistent with multiplicative noise stochastic schemes.

Earth's Topography has Power Law Structure Too



Why is topography fractal?

Jon D. Pelletier
Department of Geological Sciences, Snee Hall, Cornell University, Ithaca, New York

Figure 4. Average power spectrum S as a function of wave number k for one dimensional transects of the surface generated with the RSOS model. A least square fit to the logarithms of the ordinate and abscissa yield a slope of -1.81 indicating that $S(k) \propto k^{-1.81}$.

$$\rho \left(\frac{\partial}{\partial t} + \mathbf{u} \cdot \nabla \right) \mathbf{u} = \rho \mathbf{g} - \nabla p + \nu \nabla^2 \mathbf{u}$$

Resolved scales

Unresolved scales

Dynamical Core

$$Z = \sum_{m,l} \hat{a}_{ml} e^{iml} P_l^m(\hat{r})$$

- Discretisation errors
- Convergence errors
- Round-off errors

Parametrisations

$$P(X_{\text{Tr}}; a)$$

- Errors in the functional form of P
- Errors in the assumed values of α

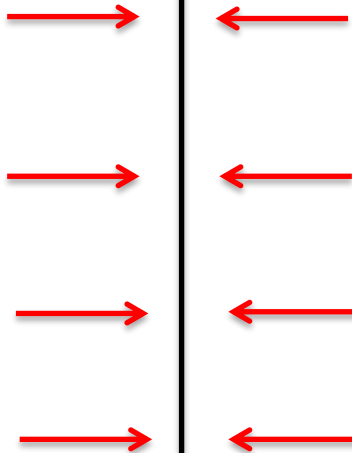
$$\rho \left(\frac{\partial}{\partial t} + \mathbf{u} \cdot \nabla \right) \mathbf{u} = \rho \mathbf{g} - \nabla p + \nu \nabla^2 \mathbf{u}$$

Resolved scales

Truncation Scale (7 to 8 orders of
magnitude above viscous scale!)

Unresolved scales

Dynamical Core



Parametrisations

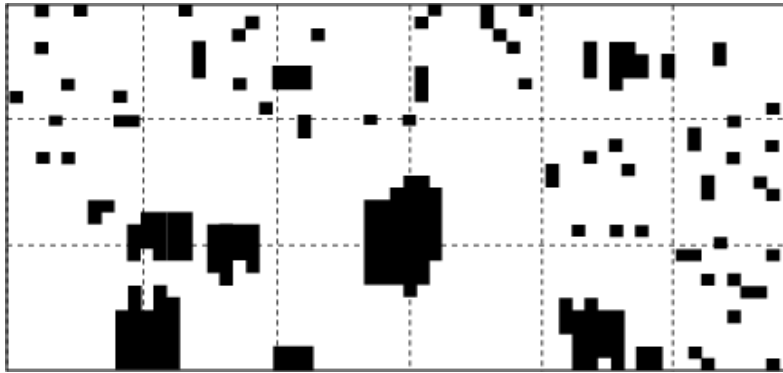


Dynamical
Core

“Physics”
Computationally cheap
stochastic-dynamic
model providing
specific realisations of
sub-grid processes

Not such a “brick wall” interface. Only makes sense in
an ensemble context. But forecasts should only made in
an ensemble context in any case!

Stochastic Cellular Automaton for Convection



Palmer 1997

Probability of an “on” cell
proportional to CAPE and
number of adjacent “on” cells
– “on” cells feedback to the
resolved flow

Stochastic Cellular Automata

TECHNICAL MEMORANDUM

669

A stochastic parameterization for deep convection using cellular automata

Lisa Bengtsson¹, Martin Steinheimer²,
Peter Bechtold³, Jean-François Geleyn⁴


Research Department

¹Swedish Meteorological and Hydrological Institute, Norrköping, Sweden
²Meteorology Department, Austro Control, Vienna, Austria
³ECMWF
⁴Météo-France, Toulouse, France

To be submitted to J. Atmos. Sci.

February 2012

This paper has not been published and should be regarded as an internal Report from ECMWF.
Permission to quote from it should be obtained from the ECMWF.



European Centre for Medium-Range Weather Forecasts
Europäisches Zentrum für mittelfristige Wettervorhersage
Centre européen pour les prévisions météorologiques à moyen terme

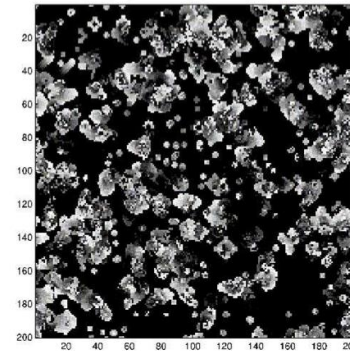


Figure 1: Example of a Cellular Automaton following the rules of Conway's game of life

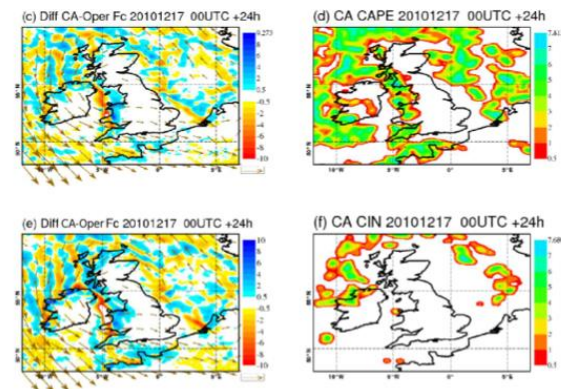
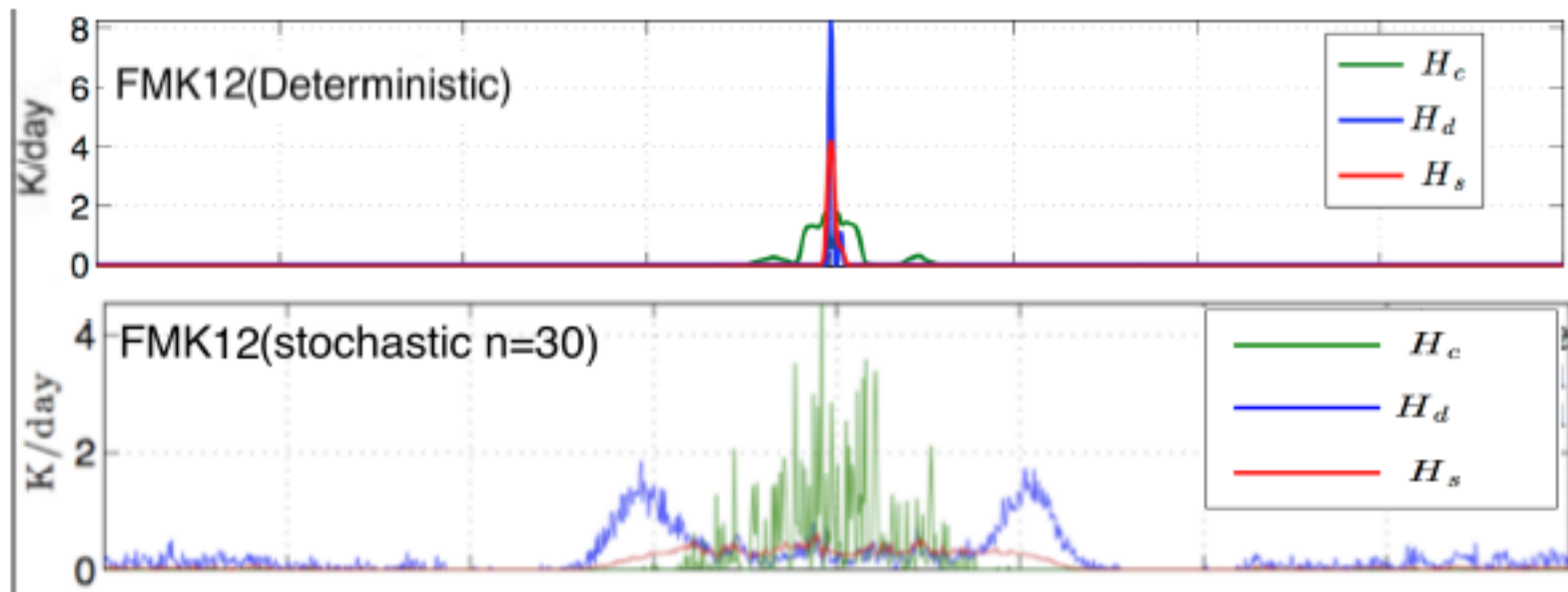


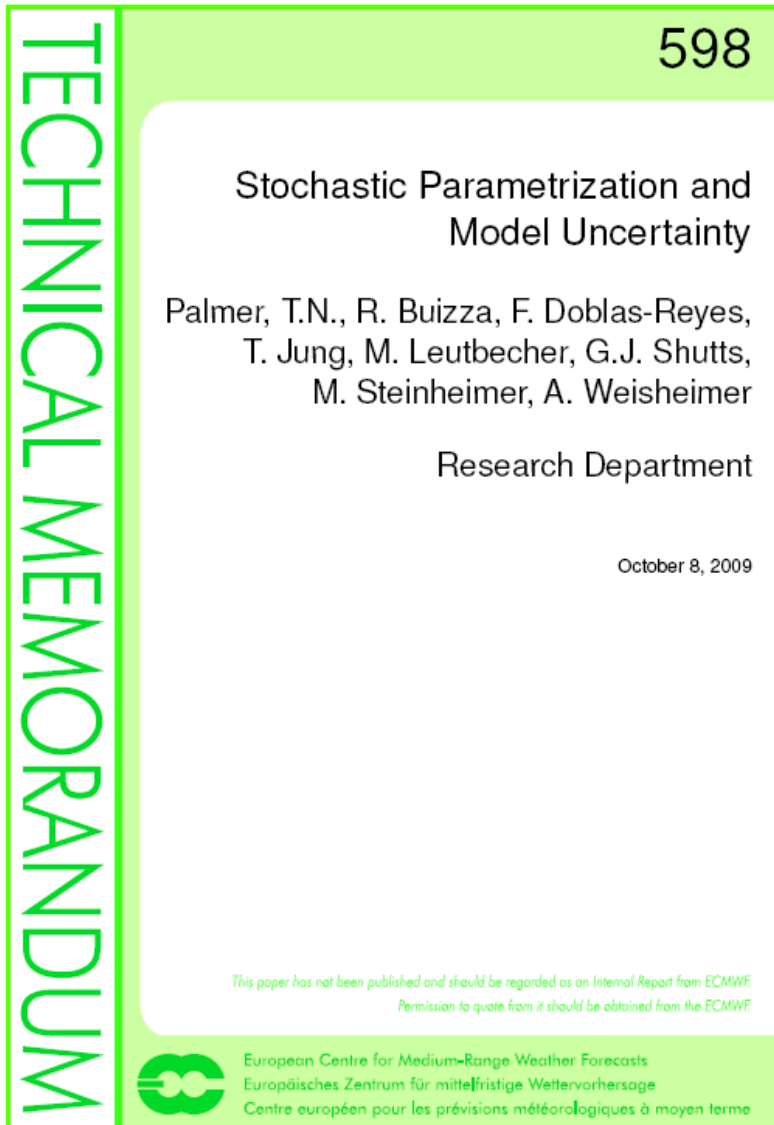
Figure 5: 24 hour accumulated precipitation (mm) on 17 December 2010 over the British Isles and Western Europe as observed by the OPERA radar network (a), the operational 24 hour deterministic IFS forecast at spectral resolution T1279=16 km (b), difference (mm) between the operational forecast and forecast using CA with CAPE seeding (c), the corresponding CA pattern for CAPE seeding (number of lives) (d), difference (mm) between the operational forecast and forecast using CA with CIN seeding (e), and corresponding CA pattern for CIN seeding (number of lives) (f)

Stochastic and Deterministic Multicloud parameterizations for tropical convection

Yevgeniy Frenkel · Andrew J. Majda ·
Boualem Khouider



Stochastic multicloud model based on a Markov chain lattice model. An extension of an Ising-type spin-flip model used for phase transitions in material science



- Multiplicative Noise – $(1+\epsilon)P$
- Operational since 1999
- Improved forecast reliability
- Reduced systematic error

Originally based on CA pattern generators, now spectral.

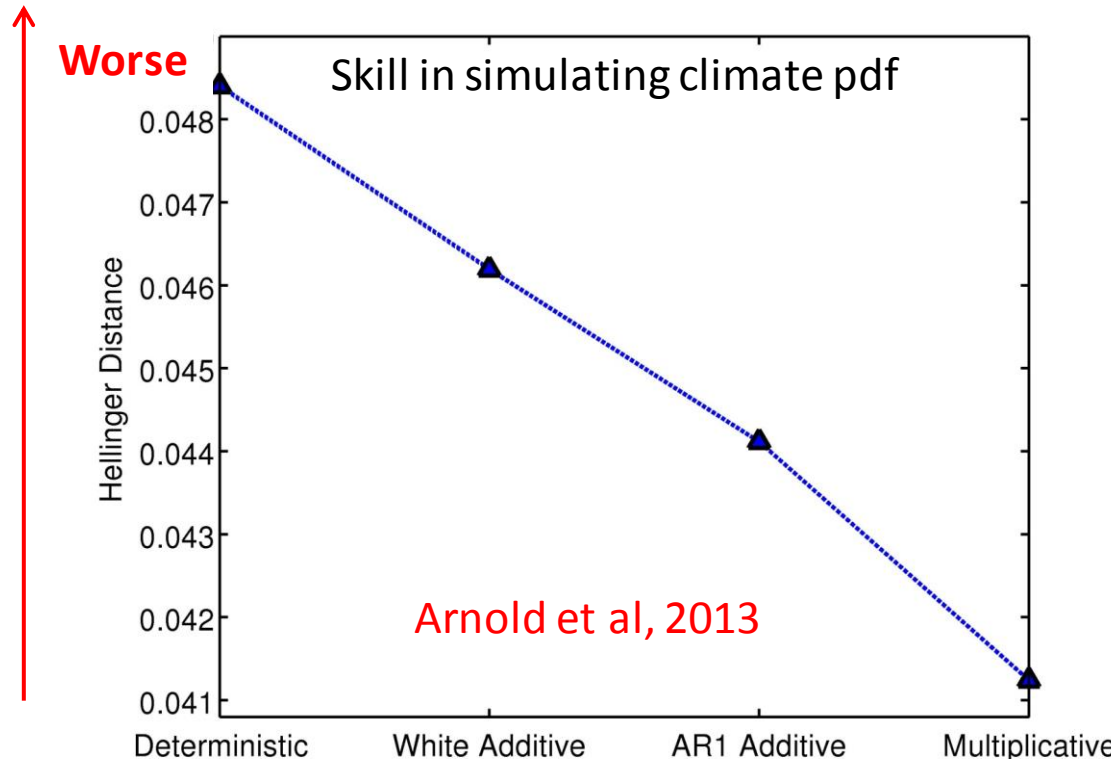
Experiments with the Lorenz '96 System (i)

$$\frac{dX_k}{dt} = -X_{k-1} (X_{k-2} - X_{k+1}) - X_k + F - \frac{hc}{b} \sum_{j=J(k-1)+k}^{kJ} Y_j$$

$$\frac{dY_j}{dt} = -cbY_{j+1} (Y_{j+2} - Y_{j-1}) - cY_j + \frac{hc}{b} X_{\text{int}[(j-1)/J+1]}$$

Assume Y
unresolved

Approximate
sub-grid
tendency by U



Deterministic: $U = U_{\text{det}}$

Additive: $U = U_{\text{det}} + e_{w,r}$

Multiplicative: $U = (1+e_r) U_{\text{det}}$

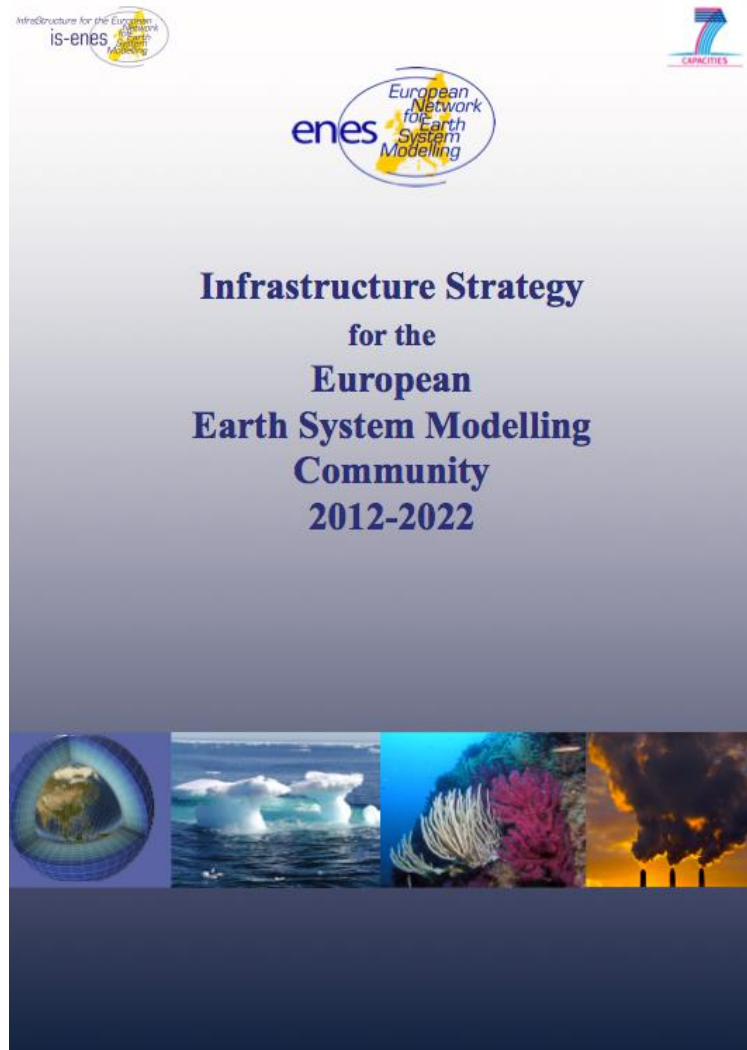
Where:

U_{det} = cubic polynomial in X

$e_{w,r}$ = white / red noise

Fit parameters from full model

iv Towards the cloud-resolved model

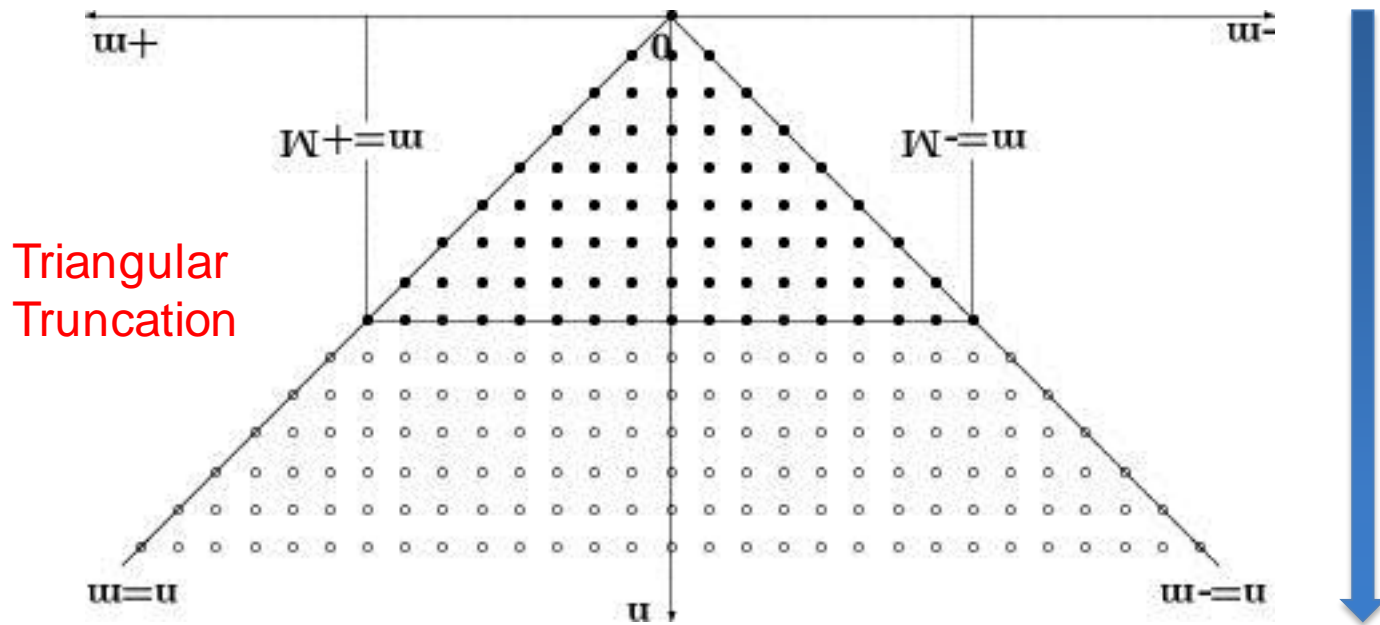


4.1 A grand challenge: Towards 1 km global resolution

A "grand challenge" for the longer term is to develop global climate models which resolve convective scale motions (nominally around 1km horizontal resolution). Although ostensibly this challenge is only about resolution, ENES believes that addressing this challenge will also support nearly all of the other scientific goals outlined earlier.

Problem:

Models make inefficient use of available HPC capability (elapsed time < 10% of peak time) and HPC is itself becoming increasingly energy intensive and hence expensive (100MWs for a bit reproducible exaflop machine?!)



Reduced Precision
arithmetic

Motivation

- Move less information

```
real(kind=8) :: a    ! I am 8 Bytes  
real(kind=4) :: b    ! I am 4 Bytes
```

- Fit more information into cache
- Lower precision arithmetic is faster

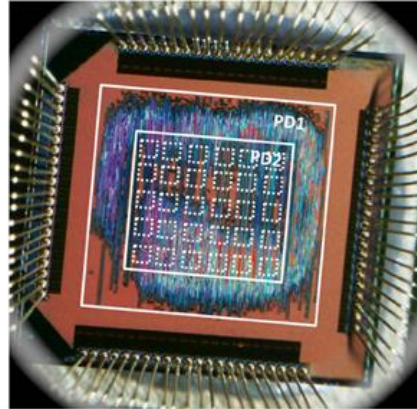
```
a = a+a-a*a*a    ! Wow, time flies!  
b = b+b-b*b*b    ! That was fast!
```

Superefficient inexact chips

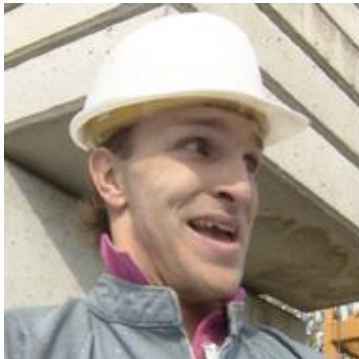
<http://news.rice.edu/2012/05/17/computing-experts-unveil-superefficient-inexact-chip/>



Krishna Palem.
Rice, NTU
Singapore



In terms of speed, energy consumption and size, inexact computer chips like this prototype, are about 15 times more efficient than today's microchips.

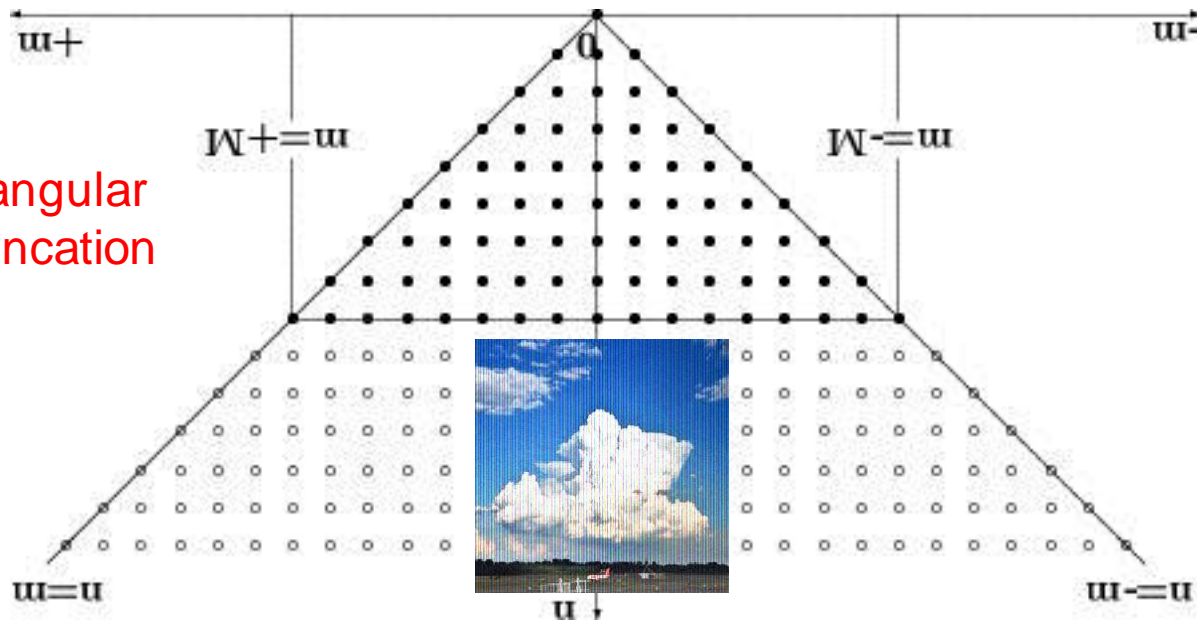


This comparison shows frames produced with video-processing software on traditional processing elements (left), inexact processing hardware with a relative error of 0.54 percent (middle) and with a relative error of 7.58 percent (right). The inexact chips are smaller, faster and consume less energy. The chip that produced the frame with the most errors (right) is about 15 times more efficient in terms of speed, space and energy than the chip that produced the pristine image (left).

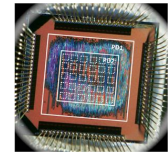


Towards the Stochastic Dynamical Core?

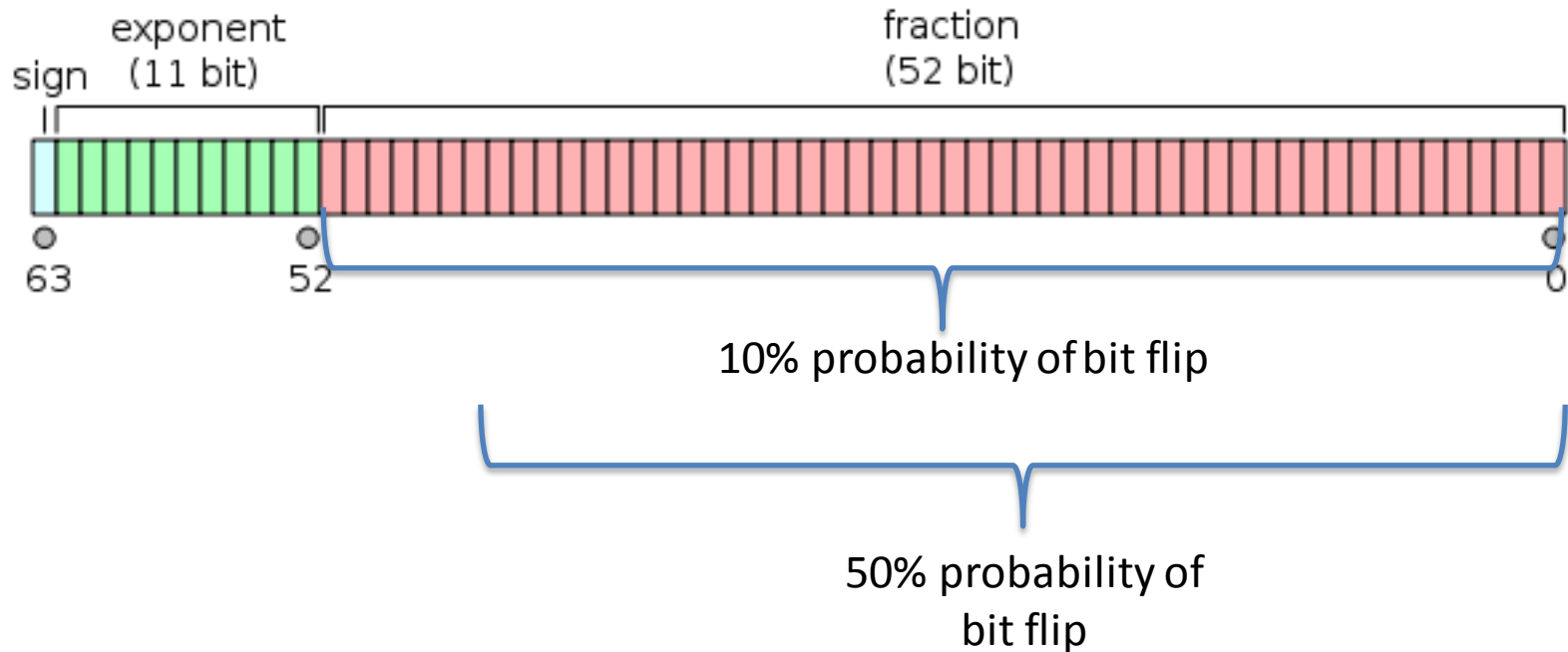
Triangular
Truncation



Inexactness of chip



Emulator of Stochastic Chip/Reduced Precision



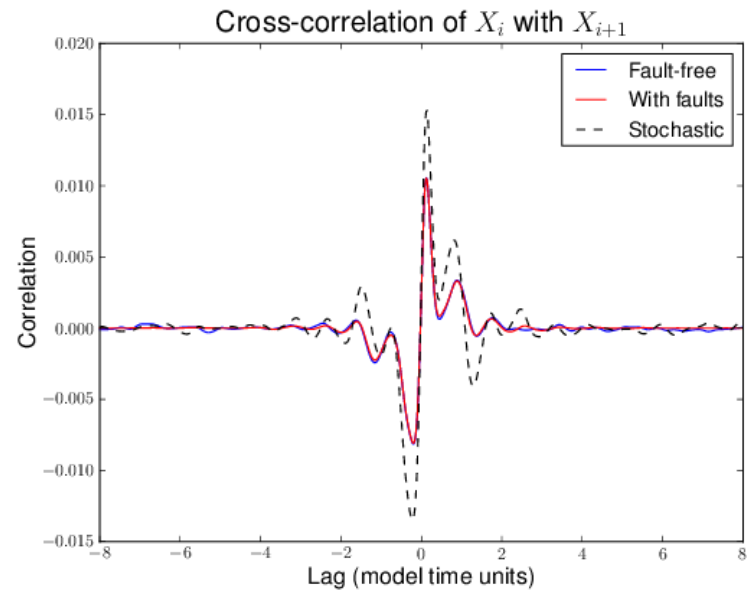
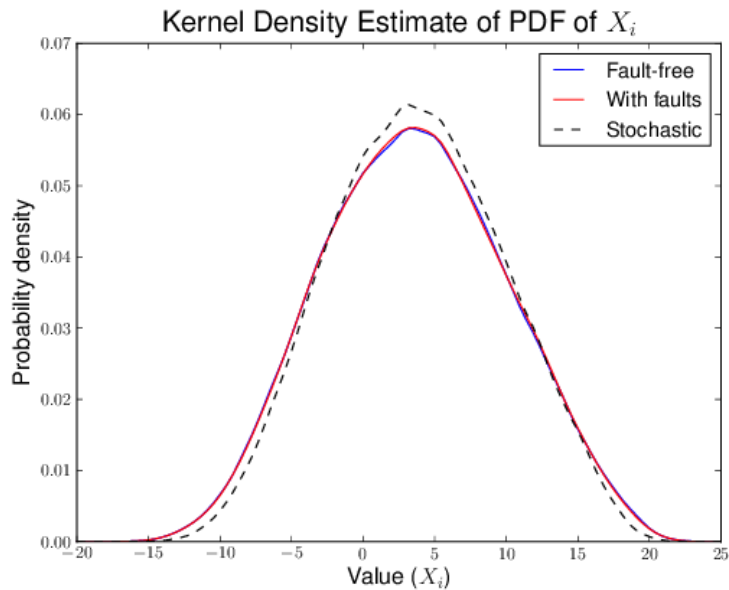
The emulator is used on 50% of numerical workload:

All floating point operations in grid point space

All floating point operations in the Legendre transforms between wavenumbers 31 and 85.

Cost approx that of T73

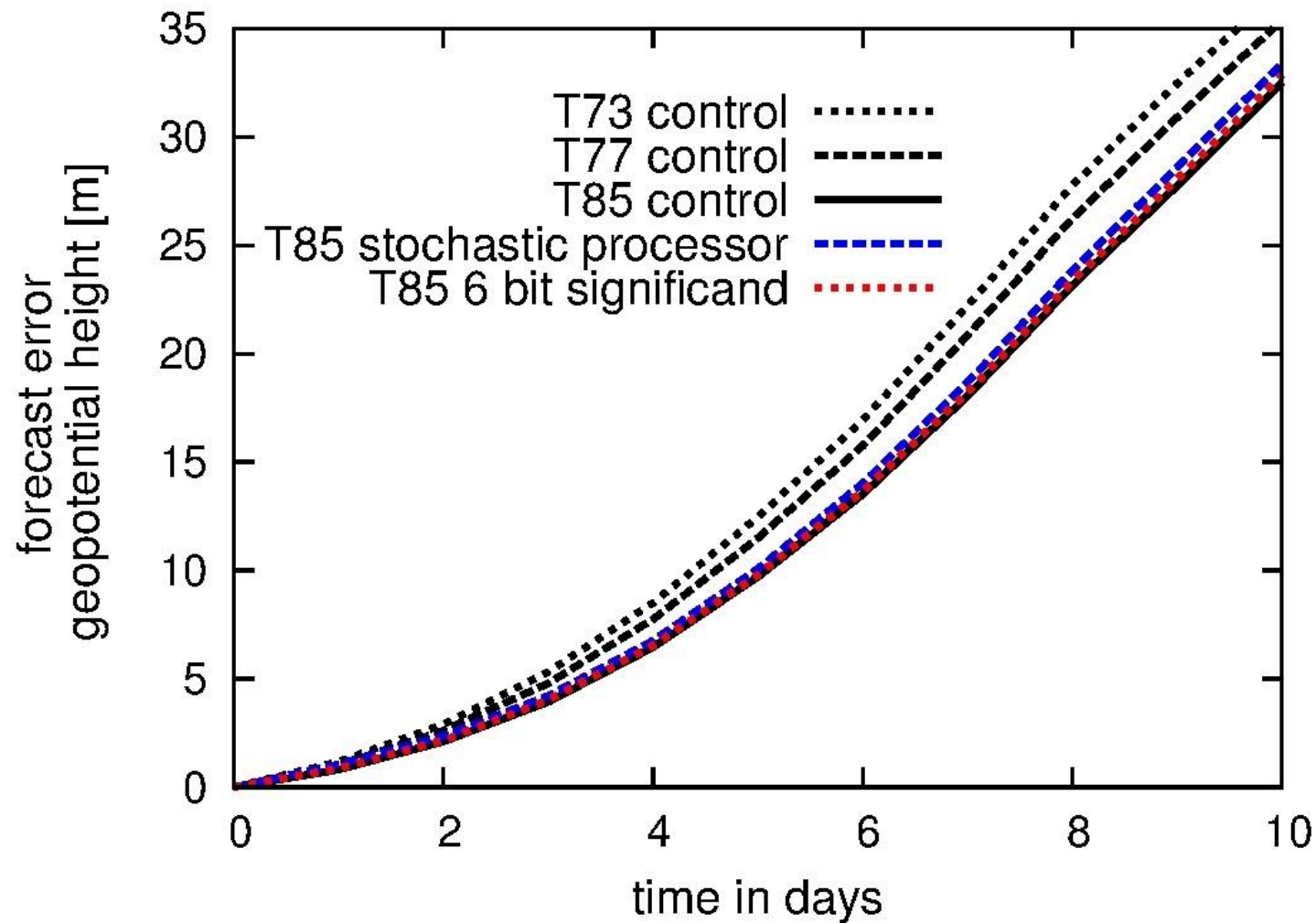
20% fault rate on Y variables



Imprecise L96 is more accurate than
parametrised L96

Hugh McNamara personal communication

Weather forecasts with imprecise processing



Peter Düben, Personal Communication

20 Years Ago

Dynamics

Parametrisation

$O(100\text{km})$
)

Now

Dynamics

Parametrisation

$O(10\text{km})$

In 10 years?

Dynamics

Parametrisation

$O(1\text{km})$